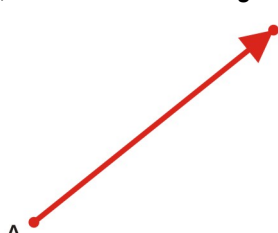
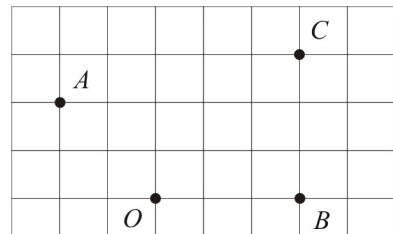
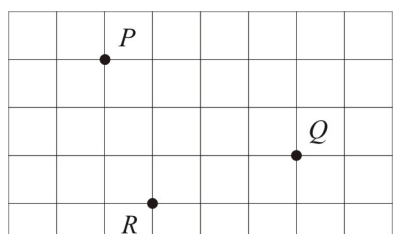


**6.1 An Introduction to Vectors**

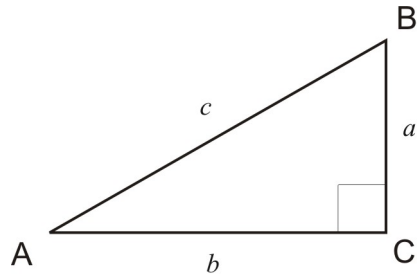
<p><b>A Scalars and Vectors</b>  <i>Scalars</i> (in Mathematics and Physics) are quantities <i>described completely by a number</i> and eventually a measurement unit.   <i>Vectors</i> are quantities described by a <i>magnitude</i> (length, intensity or size) and <i>direction</i>.</p>	<p>Ex 1. Classify each quantity as scalar or vector.                  a) time                  b) position                  c) temperature                  d) electric charge                  e) mass                  f) force                  g) displacement</p>
<p><b>B Geometric and Algebraic Vectors</b>  <i>Geometric Vectors</i> are vectors not related to any coordinate system.                  For example, the <i>directed line segment</i> <math>\overrightarrow{AB}</math>:</p>  <p>where <math>A</math> is called the initial (start, tail) point and <math>B</math> is called the final (end, terminal, head or tip) point.</p>	<p><b>C Algebraic Vectors</b>  <i>Algebraic Vectors</i> are vectors related to a coordinate system.                  These vectors are (in general) described by their <i>components</i> relative to a reference system (frame).                   For example <math>\vec{v} = (2,3,-1)</math>.</p>
<p><b>D Position Vector</b>                  The <i>position vector</i> is the directed line segment <math>\overrightarrow{OP}</math> from the origin of the coordinate system <math>O</math> to a generic point <math>P</math>.</p>	<p><b>E Displacement Vector</b>                  The <i>displacement vector</i> <math>\overrightarrow{AB}</math> is the directed line segment from the point <math>A</math> to the point <math>B</math>.</p>
<p>Ex 2. Draw the position vectors <math>\overrightarrow{OA}</math>, <math>\overrightarrow{OB}</math>, and <math>\overrightarrow{OC}</math>.</p> 	<p>Ex 3. Draw the displacement vectors <math>\overrightarrow{PQ}</math> and <math>\overrightarrow{RQ}</math>.</p> 

**G Pythagorean Theorem**

In a right triangle  $ABC$  with  $\angle C = 90^\circ$  the following relation is true:

$$c^2 = a^2 + b^2$$

(see the figure on the right side).

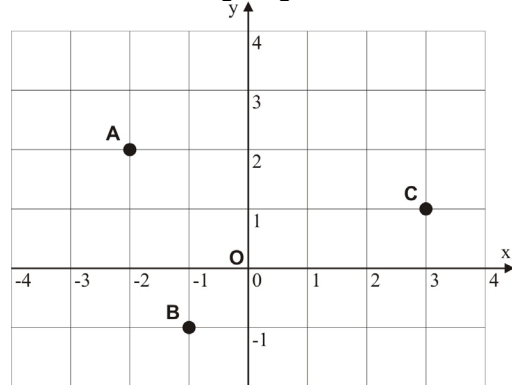


**F Magnitude**

The *magnitude* is the length, size, norm or intensity of the vector.

The magnitude of the vector  $\vec{v}$  is denoted by  $|\vec{v}|$ ,  $\|\vec{v}\|$ , or  $v$ .

Ex 4. Consider the following diagram:



Find the magnitude of the following vectors:

a)  $\vec{OA}$

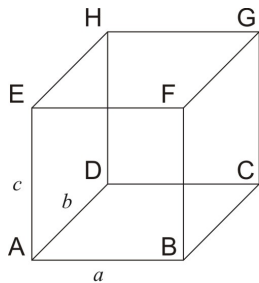
b)  $\vec{AB}$

c)  $\vec{BC}$

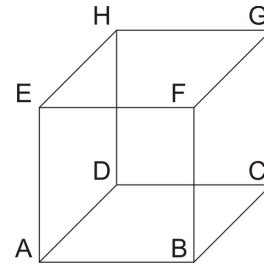
**G 3D Pythagorean Theorem**

In a *rectangular parallelepiped* (cuboid) the following relation is true:

$$AG^2 = d^2 = a^2 + b^2 + c^2$$



Ex 5. Consider the cube  $ABCDEFGH$  with the side length equal to  $10\text{cm}$ .



Find the magnitude of the following vectors:

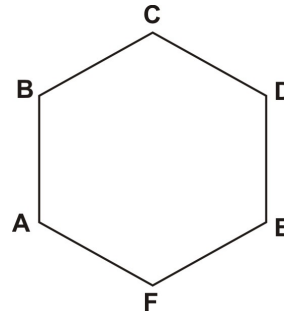
a)  $\vec{AB}$

b)  $\vec{BD}$

c)  $\vec{BH}$

Ex 6. Consider the regular hexagon  $ABCDEF$  with the side length equal to  $2m$ , represented on the right side. Find the magnitude of the following vectors:

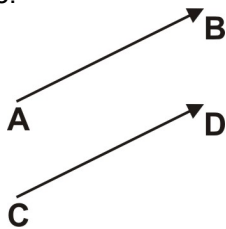
- a)  $\vec{AB}$
- b)  $\vec{AC}$
- c)  $\vec{AD}$



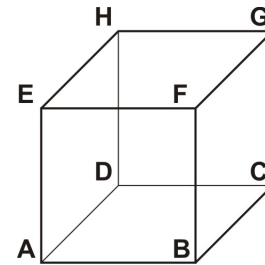
**H Equivalent or Equal Vectors**

Two vectors are *equivalent* or *equal* if they have the same magnitude and direction.

For example  $\vec{AB} = \vec{CD}$  for the vectors represented in the next figure:



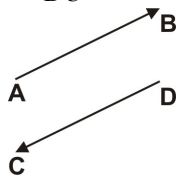
Ex 7. Find three pairs of equivalent vectors in the next diagram:



**I Opposite Vectors**

Two vectors are called *opposite* if they have the same magnitude and opposite direction.

The opposite vector of the vector  $\vec{v}$  is denoted by  $-\vec{v}$ . Example:  $\vec{AB} = -\vec{DC}$

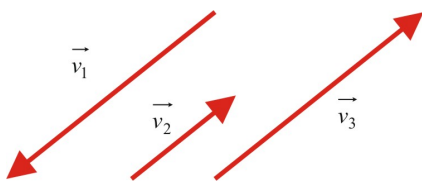


Note that  $\vec{AB} = -\vec{BA}$ .

Ex 8. Find three pairs of opposite vectors in the previous diagram.

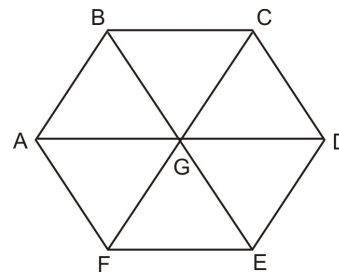
**J Parallel Vectors**

Two vectors are *parallel* if their directions are either the same or opposite.



If  $\vec{v}_1$  and  $\vec{v}_2$  are parallel, then we write  $\vec{v}_1 \parallel \vec{v}_2$ .

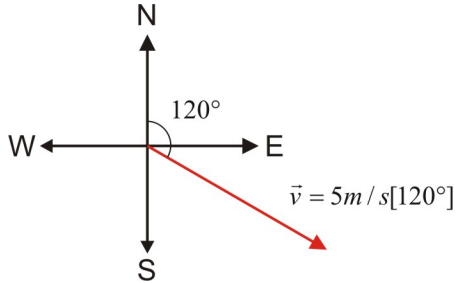
Ex 9. Use the following diagram and identify three vectors parallel to  $\vec{AG}$ .



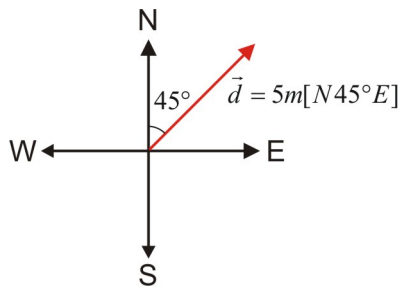
**K Direction**

To express the direction of a vector in a horizontal plane, the following standards are used.  
 Note. Because we use a reference system, the following vectors may be considered also algebraic.

*True (Azimuth) Bearing* The direction of the vector is given by the angle between the North and the vector, measured in a clockwise direction.  
 Example:  $\vec{v} = 5m / s [120^\circ]$ .



*Quadrant Bearing* The direction is given by the angle between the North-South line and the vector.  
 Example:  $5m[N45^\circ E]$ .  
 Read:  $45^\circ$  East of North.



Note.  $5m[N45^\circ E] = 5m[NE]$   
 Read:  $5m$  North-East.

Ex 10. Draw each vector given by magnitude and true bearing.

- a)  $\vec{r} = 2m$  at a true bearing of  $[060^\circ]$
- b)  $\vec{a} = 5m / s^2 [225^\circ]$

Ex 11. Draw each vectors given by magnitude and quadrant bearing.

- a)  $\vec{d} = 2m[S60^\circ E]$
- b)  $\vec{F} = 10N[W]$

Ex 12. Convert each vector.

- a)  $\vec{v} = 5m / s [210^\circ]$  (to quadrant bearing)
- b)  $\vec{d} = 25m[N30^\circ W]$  (to true bearing)

**Reading:** Nelson Textbook, Pages 275-278

**Homework:** Nelson Textbook: Page 279 #1, 4, 6, 8, 9, 11